M91-19-4R1

12/24 VDC, 10 pnp/npn digital inputs, 1 analog input, 3 high-speed counter/shaft encoder inputs, 6 relay outputs, I/O expansion port, RS232/RS485 port

Power supply	12VDC or 24VDC
Permissible range	10.2VDC to 28.8VDC with less than 10% ripple
Maximum current consumption	180mA@24VDC (pnp inputs) 260mA@24VDC (npn inputs) 220mA@12VDC (pnp inputs) 330mA@12VDC (npn inputs)
Digital inputs	10 pnp (source) or npn (sink) inputs. See Note 1.
Nominal input voltage	12VDC or 24VDC. See Notes 2 and 3.
Input voltages for pnp (source): For 12VDC For 24VDC	 0-3VDC for Logic '0' 8-15.6VDC for Logic '1' 0-5VDC for Logic '0' 17-28.8VDC for Logic '1'
Input voltages for npn (sink): For 12VDC For 24VDC	 8-15.6VDC/<1.2mA for Logic '0' 0-3VDC/>3mA for Logic '1' 17-28.8VDC/<2mA for Logic '0' 0-5VDC/>6mA for Logic '1'
Input current	4mA@12VDC 8mA@24VDC
Input impedance	3KΩ
Response time (except high-speed inputs)	10mS typical
Galvanic isolation	None
Input cable length	Up to 100 meters, unshielded
High-speed counter	Specifications below apply when inputs are wired for use as a high-speed counter input/shaft encoder. See Notes 4 and 5.
Resolution	16-bit
Input freq.	10kHz max.
Minimum pulse	40µs

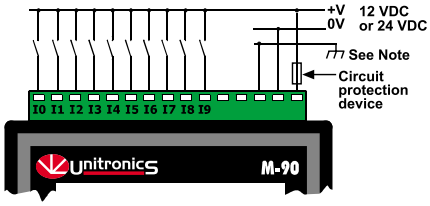
Notes:

1. All 10 inputs can be set to pnp (source) or npn (sink) via a single jumper and appropriate wiring.
2. All 10 inputs can function in 12 VDC or 24 VDC; set via a single jumper and appropriate wiring.
3. npn (sink) inputs use voltage supplied from the controller's power supply.
4. Inputs #0, #2 and #4 can each function as either high-speed counter or as part of a shaft encoder. In each case, high-speed input specifications apply. When used as a normal digital input, normal input specifications apply.
5. Inputs #1, #3 and #5 can each function as either counter reset, or as a normal digital input; in either case, specifications are those of a normal digital input.
   These inputs may also be used as part of a shaft encoder.
   In this case, high-speed input specifications apply.

Warnings:

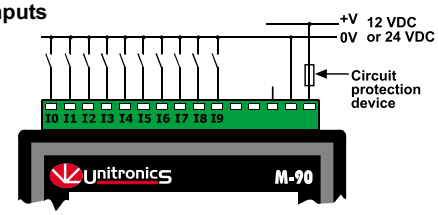
- Unused pins should not be connected. Ignoring this directive may damage the controller.
- Improper use of this product may severely damage the controller.
- Refer to the controller's User Guide regarding wiring considerations.
- Before using this product, it is the responsibility of the user to read the product's User Guide and all accompanying documentation.

Power supply, pnp (source) inputs

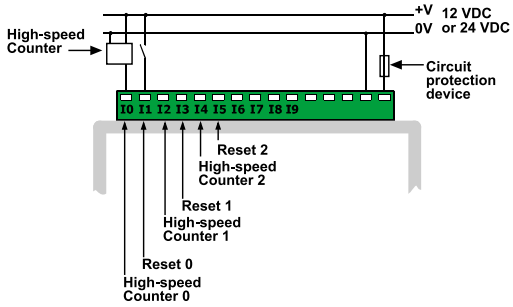


Note:
To avoid electromagnetic interference, mount the controller in a metal panel/cabinet and earth the power supply. Earth the power supply signal to the metal using a wire whose length does not exceed 10cm. If your conditions do not permit this, do not earth the power supply.

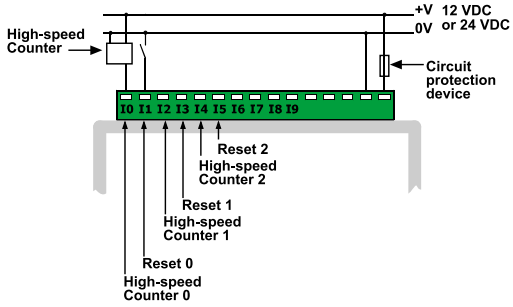
npn (sink) inputs



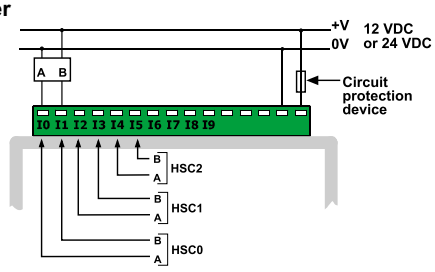
pnp (source) high-speed counter



npn (sink) high-speed counter



Shaft encoder



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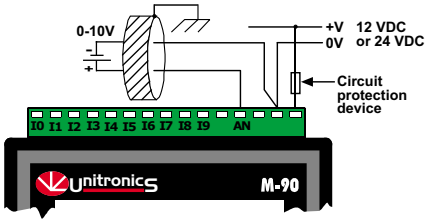
Analog Input	10-bit, multi-range input: 0-10V 0-20mA, 4-20mA
Conversion method	Successive approximation
Input impedance	>100KΩ for voltage 500Ω for current
Galvanic isolation	None
Resolution (except 4-20mA)	10-bit (1024 units)
Resolution at 4-20mA	204 to 1023 (820 units)
Conversion time	Synchronized to scan time
Absolute max. rating	±15V
Full scale error	± 2 LSB
Linearity error	± 2 LSB
Status indication	Yes, see Note

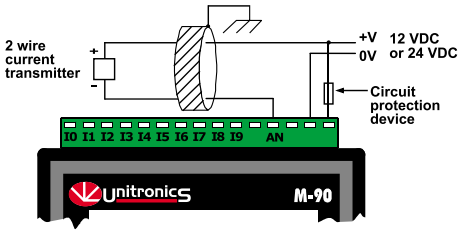
Note:
The analog value can also indicate when the input is functioning out of range. If an analog input deviates above the permissible range, its value will be 1024.

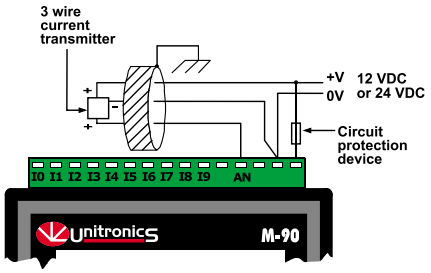
Voltage connection

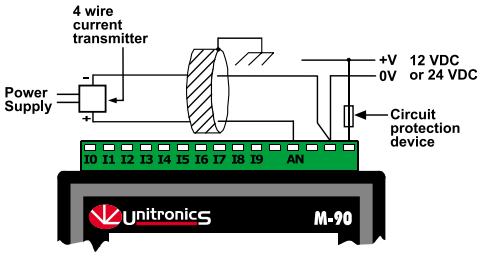


Notes:
a. Shields should be connected at the signals' source.
b. The 0V signal of the analog input must be connected to the controller's 0V.

Current connections



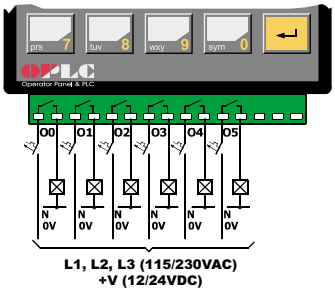




Notes:
a. Shields should be connected at the signals' source.
b. The 0V signal of the analog input must be connected to the controller's 0V.

Digital outputs	6 relay outputs, 230VAC/ 12/24VDC
Output type	SPST-NO relay
Type of relay	Takamisawa (Fujitsu) JY-12H-K, or NAIS (Matsushita) JQ1A-12V or OMRON G6B-1114P-12VDC
Isolation	by relay
Output current	5A max. (resistive load) 1A max. (inductive load)
Max. frequency	10Hz
Contact protection	External precautions required

Relay Outputs



Display	STN, LCD display
Illumination	LED yellow-green backlight
Display size	1 line, 16 characters long
Character size	5 x 7 matrix, 3.07 x 5.73mm
Keypad	Sealed membrane
Number of keys	15

PLC program	
Ladder Code Memory (virtual)	24K
Memory Bits (coils)	256
Memory Integers (Registers)	256
Timers	64
Execution time	12µsec. for bit operations
Database	1024 integers (indirect access)
HMI displays	80 user-designed displays
HMI variables	50 HMI variables are available to conditionally display and modify text, numbers, dates, times & timer values. The user can also create a list of up to 120 variable text displays, totaling up to 2K.

RS232/RS485 serial port	Used for: ● Application Download/Upload ● Application Testing (Debug) mode ● Connect to GSM or standard telephone modem: - Send/receive SMS messages - Remote access programming ● RS485 Networking
RS232 (see note)	1 port
Galvanic isolation	None
Voltage limits	±20V
RS485 (see note)	1 port
Input voltage	-7 to +12V differential max.
Cable type	Shielded twisted pair, in compliance with EIA RS485
Galvanic isolation	None
Baud rate	110 – 57600 bps
Nodes	Up to 32

Note:
RS232/RS485 is determined by jumper settings and wiring, as described in the document "M91 RS485 Port Settings" packaged with the controller.

I/O expansion port	Up to 64 additional I/Os, including digital & analog I/Os, RTD & more.

Miscellaneous	
Clock (RTC)	Date and time-year 2000 compliant.
Battery back-up	7 years typical battery back-up for RTC and system data.
Weight	310g (10.9 oz.)
Operational temperature	0 to 50°C (32 to 122°F)
Storage temperature	-20 to 60°C (-4 to 140°F)
Relative Humidity (RH)	5% to 95% (non-condensing)
Mounting method	DIN-rail mounted (IP20/NEMA1) Panel mounted (IP65/NEMA4X)

M91-19-4R1

Jumper Settings

The tables below show how to set a specific jumper to change the functionality of the controller.
To open the controller and access the jumpers, refer to the directions at the end of these specifications.

Important:
Incompatible jumper settings and wiring connections may severely damage the controller.

JP1
Digital inputs type

To use as	JP1
npn (sink)	A
pnp (source)*	B

JP5, JP6
Power supply voltage

Range	JP5	JP6
10.2 to 15.6VDC	A	A
15.6 to 28.8VDC*	B	B

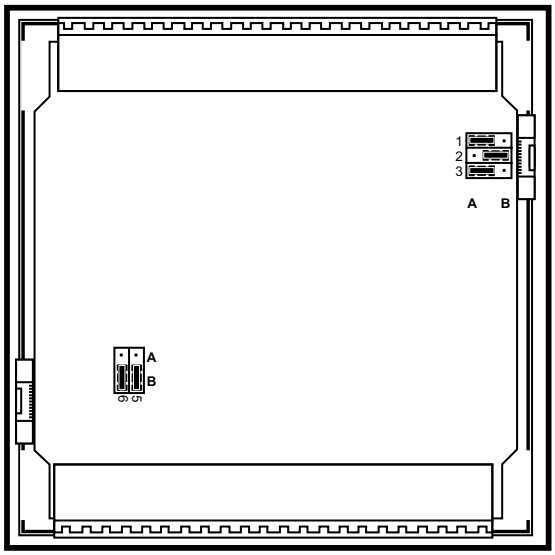
JP2
Digital inputs voltage

To use as	JP2
12VDC	A
24VDC*	B

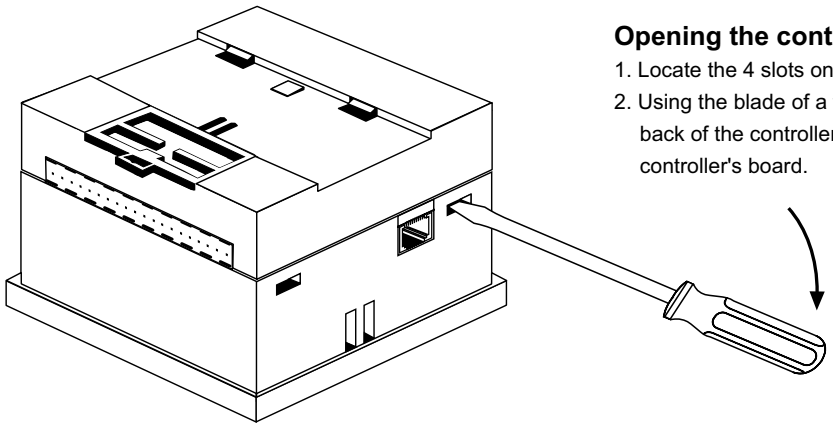
JP3
Analog input type

To use as	JP3
Voltage input*	A
Current input	B

*Default factory setting



In this figure, the jumper settings will cause the controller to function as follows:
Digital inputs: npn, 24VDC inputs
Analog input: Voltage input
Power supply: 24VDC



Opening the controller enclosure

1. Locate the 4 slots on the sides of the enclosure
2. Using the blade of a flat-bladed screwdriver, gently pry off the back of the controller as shown in the figure below, exposing the controller's board.

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