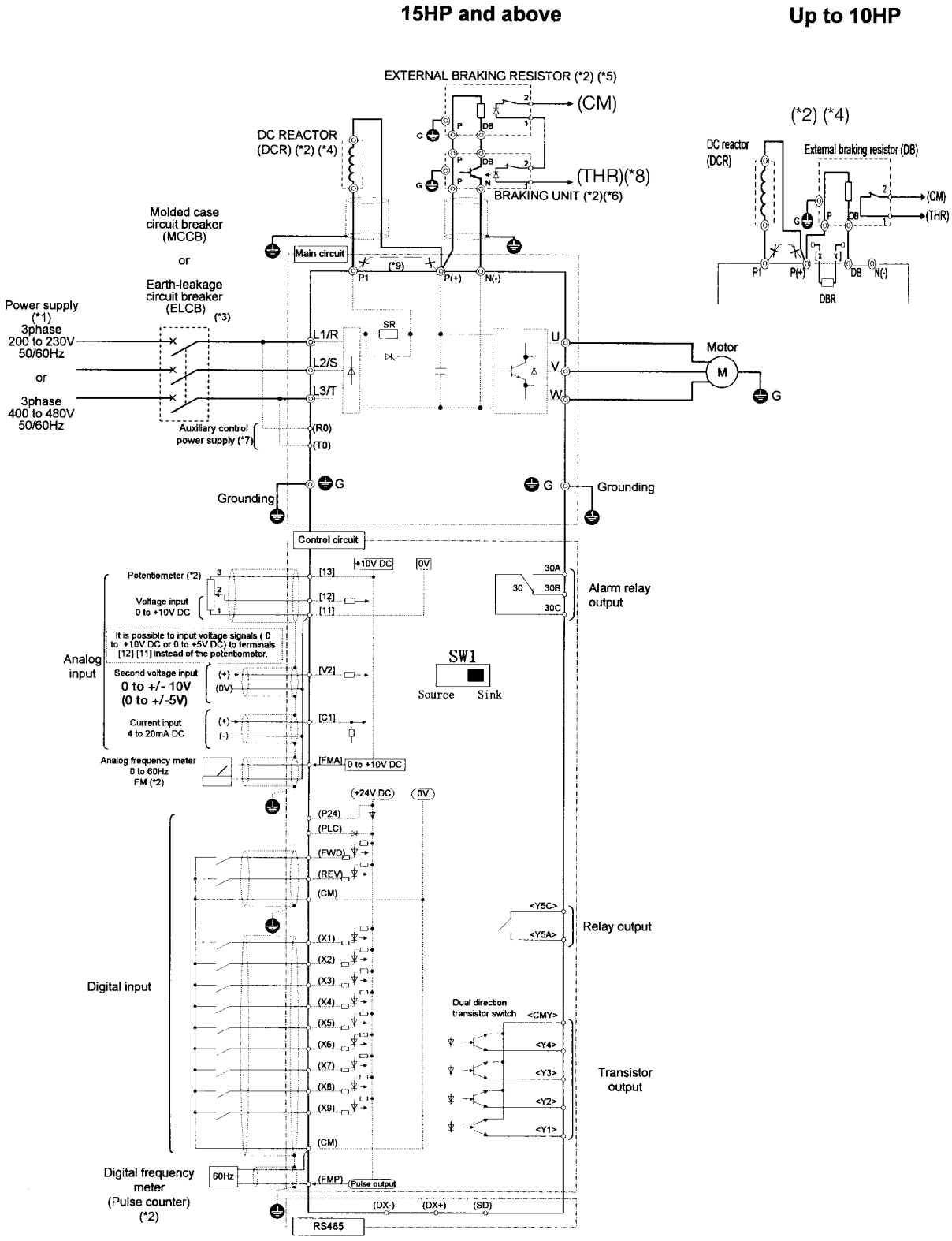
efesotomasyon.com - Control Techniques,emerson,saftronics -ac drive-servo motor

Basic Connection Diagram (Sink Logic, Mainly America)



Note: The control circuit common terminals [11], (CM) and <CME> are isolated

(*1) Use a drive with rated voltage matching the power supply voltage.
(*2) Option. Use as required.
(*3) Use this peripheral device when necessary.
(*4) Remove the jumper wire (*9) between P1 and P(+) before connecting a DC REACTOR.
(*5) Be sure to use the braking unit (option)(*6) when connecting the externa; braking resistor (option)(*5)
(*6) Connect the braking unit to P(+) ans N(-). The auxiliary terminals [1] ans [2] have polarity. Connect them as shown in figure above.
(*7) The drive can be operated without connecting the auxiliary control power supply.
(*8) Terminal (X1) to (X9) can be preset (THR) ("E01 to E09: 9).